openHAB
empowering the smart home

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👤 **openhabian**
http://192.168.1.91:8080

Thing	Channels	Code

JS(divide1000.js)   ⊗

Transformation to apply to polled data, after it has been converted to number using readValueType

Use "default" to communicate that no transformation is done and value should be passed as is.
Use SERVICENAME(ARG) to use transformation service.

Any other value than the above types will be interpreted as static text, in which case the actual content of the polled value is ignored.

Read Value Type   16bit signed integer (int16) ›

How data is read from modbus. Use empty for write-only things.

With registers all value types are applicable.

Write Address

Start address of the first holding register or coil in the write. Use empty for read-only things.
Use zero based address, e.g. in place of 400001 (first holding register), use the address 0. This address is passed to data frame as is.

Write Type

◯ coil, or digital out (DO)

◯ holding register

Type of data to write. Leave empty for read-only things.

Coil uses function code (FC) FC05 or FC15. Holding register uses FC06 or FC16. See writeMultipleEvenWithSingleRegisterOrCoil parameter.

Write Transform
default   ⊗

Transformation to apply to received commands.

Use "default" to communicate that no transformation is done and value should be passed as is.
Use SERVICENAME(ARG) to use transformation service.
Any other value than the above types will be interpreted as static text, in which case the actual content of the command value is ignored.

Write Value Type   ›

How data is written to modbus. Only applicable to registers, you can leave this undefined for coil.